



Timing Distribution System (TDS)

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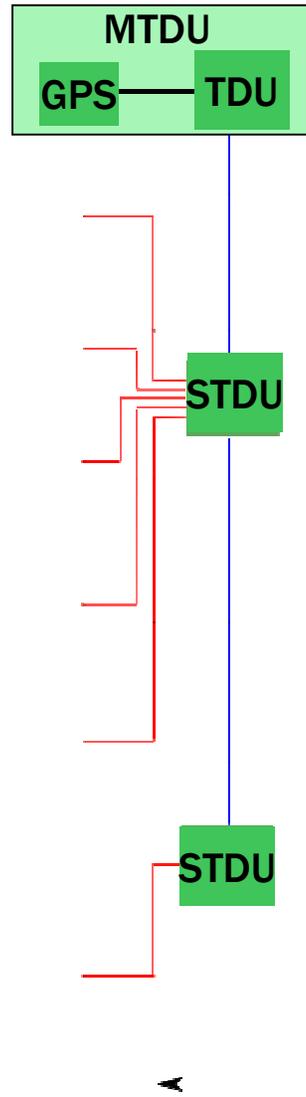


NOvA Timing Distribution System Features

- Distributes system clock and synchronizes time stamp registers of all DAQ devices on detector.
- All timing system links are CAT5e cables except Near Detector MTDU to STDU1 (need fiber to go the 200 or so meters).
- Configurable and monitorable via DCS.
- DCMs have two clock system interfaces, so a complete redundant clock system can be deployed if desired.
- Can correct for cable delays using TOF/2 method if desired.

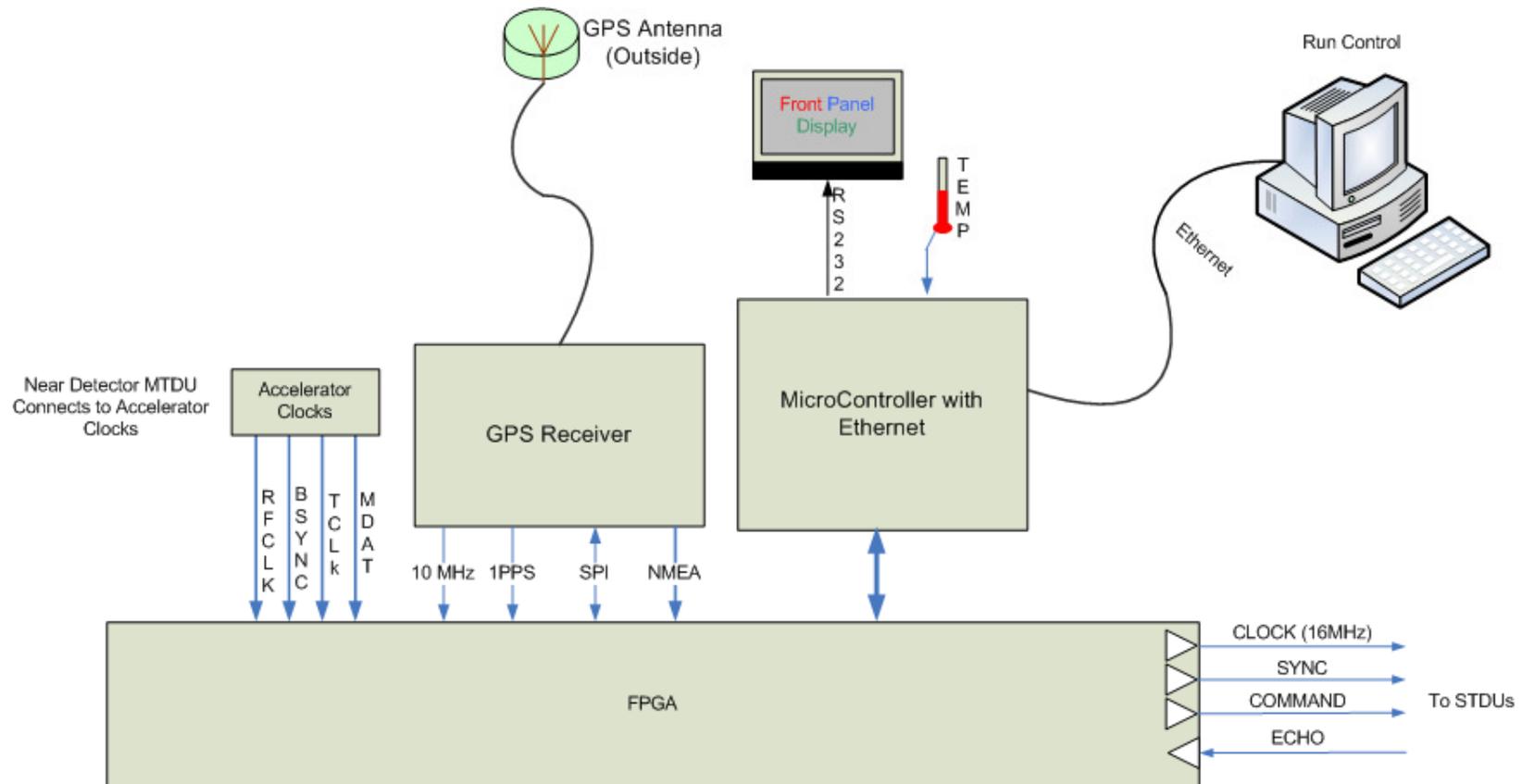


TDS to DAQ System



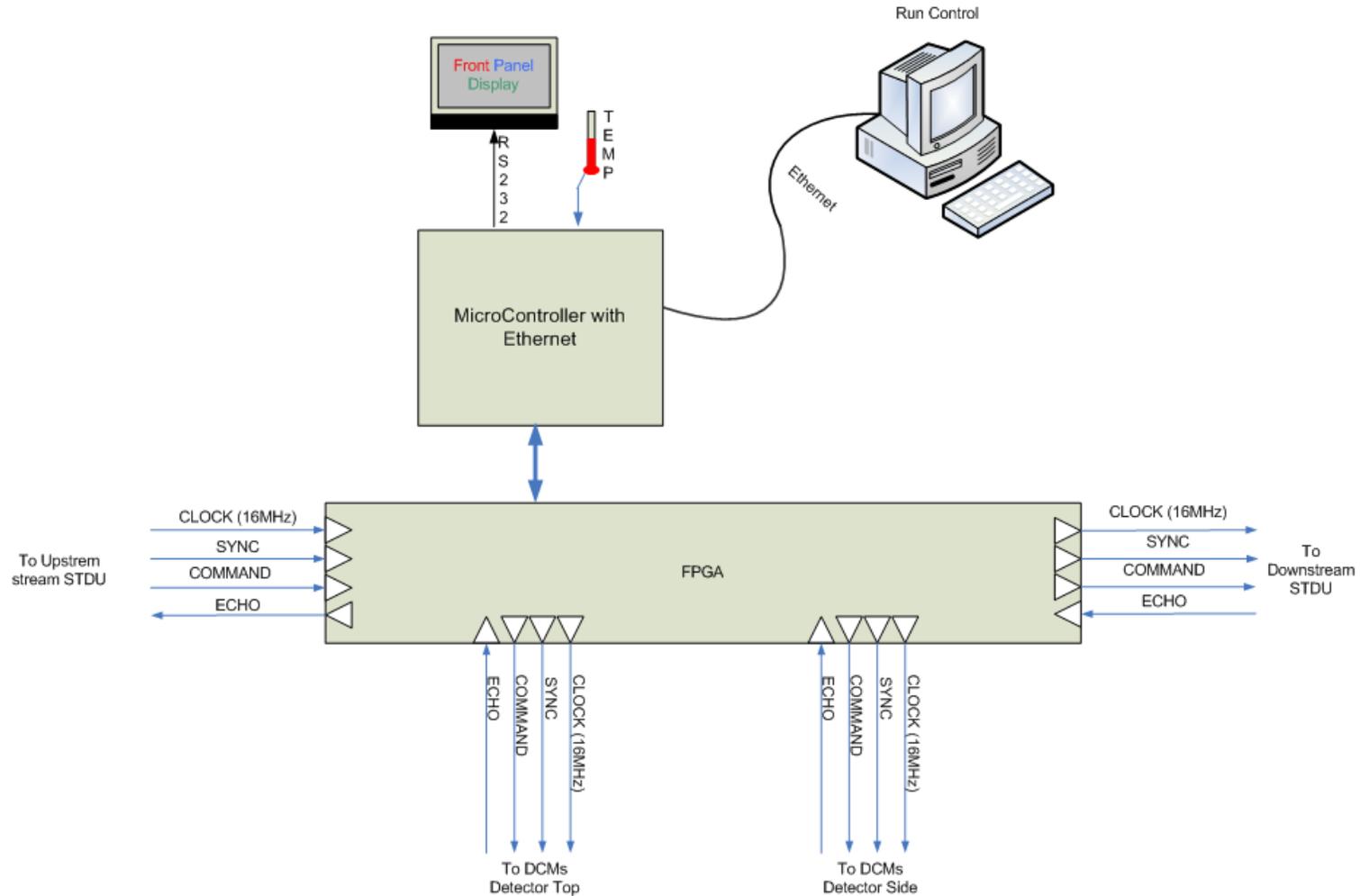


Master Timing Unit





Slave Timing Unit





Some Functional Details

- Timing system's main connection to DCS is to MTDU via Ethernet.
- Timing critical commands are transmitted to system from MTDU through timing links.
- Timing critical events are synchronized with SYNC signal on timing links (generated by MTDU).
- STDU can be queried for status via Ethernet, but cannot inject commands or SYNCs.
- MTDU and STDU firmware remotely loadable via Ethernet.



On System Startup...

- MTDU put into “Delay Learn” mode.
 - Transmits a SYNC pulse to slaves.
 - Measures time of round trip via ECHO signal.
 - All STDUs and DCMs do the same.
- MTDU synchronizes timing registers in all DAQ devices.
 - Transmits Timing Register Preset command.
 - Issues SYNC to start Timing Counter on all devices on the same clock cycle.
- MTDU issues command(s) to set mode in all DCMs and FEBs.
 - FEB and DCM control registers write accessible via timing link.
- MTDU periodically issues a Timing Register Verify command as a sanity check.



MTDU



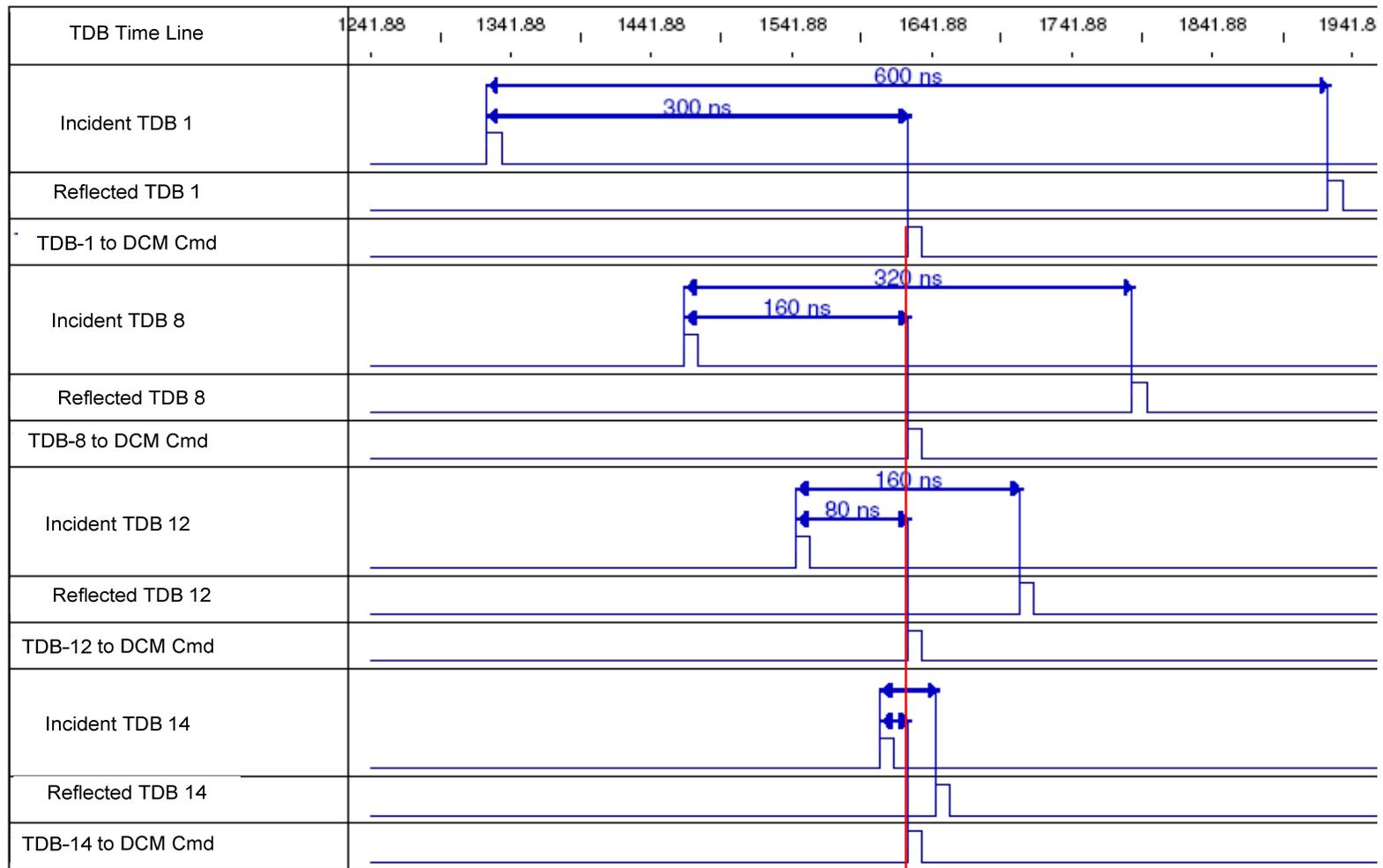


GPS Module





TOF/2 (Time of Flight / 2)



All TDS's Trigger
Simultaneously



Schedule & Summary

- We have two assembled prototype TDU modules (STDU and MTDU use same board). Hardware is working.
- We have four GPS units and four antennas.
- We expect to have two assembled CPU daughter boards and two more TDU modules by end of month.
- For NDOS we will need:
 - One Master Timing unit.
 - One CPU daughter board.
 - One GPS module and antenna.
 - 1 Slave Timing Distribution unit (two would be nice).
- We expect to have firmware working that will be functional but may not be 100% feature complete.



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Questions?



Supporting Notes

- Following are notes of the above slides



Master Timer

- Incorporates a common view GPS trained clock generator with a time-stamp counter.
- Capable of decoding Fermilab beam timing signals (RF-Clk, BSync, TClk, MDat).
- Capable of broadcasting time-of-day and time-stamp to Far Detector (100Mb ethernet).
- Provides a USB slave port (alternate computer connection).
- Provides repetitive timing & control packets to downstream distribution boxes.
- Measures & stores roundtrip time-of-flight of timing commands.



Timing Distribution Unit

- Coherent timing along the backbone of the detector.
 - Timing is referenced to the far-end cable loopback.
 - Synchronization is within +/- 1/2 clock cycle (16.834Mhz).
- Synchronization is based on the roundtrip time-of-flight of timing packets.
 - Digital equivalent of the time-of-flight of a reflection on a coax cable using a Time Domain Reflectometer.
 - Time-of-flight measurements are stored for later readout.
- Propagation delays are self compensated
 - No need to match cable pair lengths (xmt & rcv)
- Distributes Clock, Timing & Control commands to DCMs



Timing Distribution System (old design)

